

# Route Planning and Situated Navigation in Collaborative Wayfinding

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## Research Questions

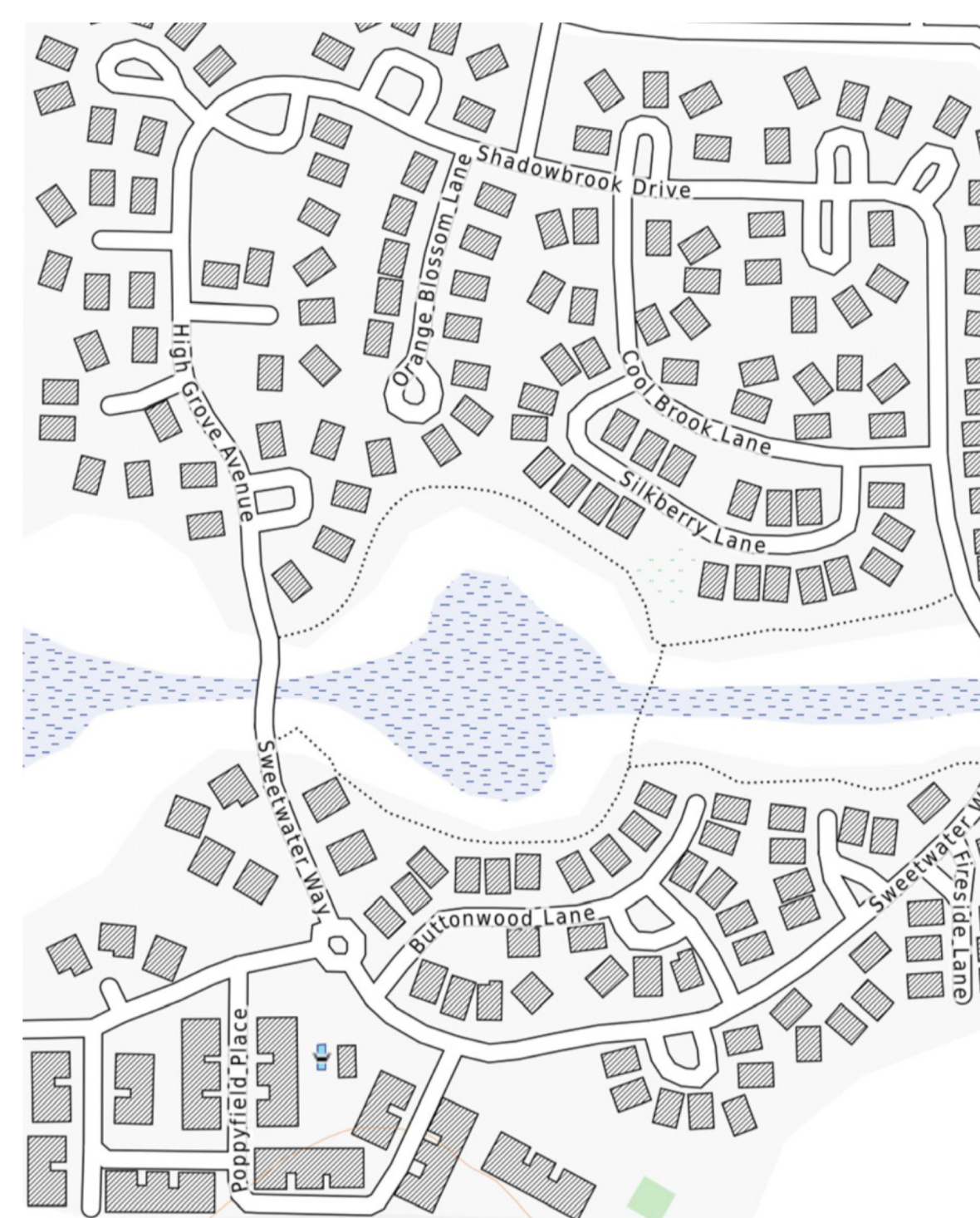
**Primary: How do dyads (pairs) work together to plan navigational routes through a novel environment?**

- What characterizes prospective paired planning versus situated paired planning of a route?
- How do route planning strategies differ based on individual differences in spatial ability, for instance as self-reported through existing sense of direction (SOD) measures?

**Secondary: How do dyads coordinate their knowledge and behavior in a real-world spatial navigation task?**

- How efficient are different pairs of people in their navigation task performance, in terms of time and distance minimization? Which social interactive factors contribute to this performance?
- How, when, and to what end are leadership and following roles adopted within the dyadic interaction?
- How and when do individuals communicate trouble to their wayfinding partner, including social trouble or wayfinding uncertainty?

## Study Description



Participants ( $n = 48$  so far) collaborated on a task to both **plan** and **execute** a pedestrian route between a given origin and destination.

Interactions during both planning and navigation were **video-recorded** and will be coded for navigational strategies and interactional behavior.

## Measures

### Individual Measures of Spatial Ability and Personality

#### Santa Barbara Sense of Direction (SBSOD)

Self-report assessment of spatial ability, ranging from 1.0 to 7.0

- Individual SOD may relate to navigational success or flexibility in map-reading or interpretation
- Within-pair SOD differences may relate to joint navigational success or strategy use

#### Big Five Personality Inventory (BFI)

Assessment of personality characteristics along the dimensions of *Extraversion*, *Agreeableness*, *Conscientiousness*, *Neuroticism*, and *Openness to New Experience*

- Relate BFI characteristics to planning and wayfinding strategies, as well as within-pair leadership

## Methodology

### Phase I: Planning

- Participants were recruited into dyads with no prior familiarity with each other or the study site
- Each dyad was given a map with origin and destination points between which they had to plan a route (while video-recorded)
- Individuals were asked to draw and describe the planned route



### Phase II: Navigation



- Dyads were taken to the study site and asked to navigate between the same origin and destination points as in the planning phase
- Participants wore a video camera and were GPS-tracked

## Preliminary Results

- Wide variety in planned routes across dyads, with distances ranging from 0.36 to 0.61 miles
- Length of route during navigation phase ranged from 0.40 to 1.33 miles and averaged 0.63 miles
- Observed differences in planned routes and routes as executed *in situ* – shortcutting or getting lost
- Time ranged from 8 to 29 min, average 12.6 minutes

### Profiles of Dyads

Dyad ID	Sex Pairing	SBSOD Difference [Individual Levels*]	Time Taken to Completion	Self-reported Social Role-taking
1	M / F	0.20 [Low/Low]	10:42	Leader & Follower
2	F / F	0.53 [High/High]	23:50	Leader & Follower
3	F / F	1.33 [High/Low]	9:44	Collaborative
4	M / F	2.53 [High/Low]	8:37	Leader & Follower
5	F / F	0.93 [High/Low]	9:03	Collaborative
6	F / F	1.47 [High/Low]	10:46	Collaborative
7	F / F	0.53 [Low/Low]	7:05	Collaborative
8	F / F	1.53 [High/Low]	8:08	Leader & Follower

\*Median SBSOD score of 4.1 used to categorize participants as "high" or "low" SBSOD.

## Next Steps

- Code video recordings of planning phases, focusing on route suggestion sequences
- Code video recordings of navigation phases, with attention to coordinating spatial understanding and actions at decision points

### Selected References

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